Densest Subgraph: Supermodularity, and Iterative Peeling

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# Densest Subgraph (DSG)

G = (V, E) undirected graph Find "dense" subgraph(s)

$$density(S) = \frac{|E(S)|}{|S|}$$
$$\lambda^* = \max_{S \subseteq V} \frac{|E(S)|}{|S|}$$



### Dense Subgraph Discovery

 $density(S) = \frac{f(S)}{|S|}$ 

- Triangle density: f(S) = # of triangles in G[S] [Tsourakakis'14]
- k-clique density: f(S) = # of k-cliques in G[S] [Tsourakakis'15]
- Hypergraphs: f(S) = # of hyperedges in G[S] [folklore?]
- p-mean density:  $f(S) = \sum_{v \in S} \deg(v, S)^p$  [Benson-Kleinberg-Veldt'21]
- Constrained versions: [many authors]  $\max f(S) s. t |S| = k, |S| \le k, |S| \ge k$
- Directed graph version: [Kannan-Vinay'99, Charikar'00]

# Polynomial Solvability

DSG is poly-time solvable

- Reduction to flow [Picard-Queyranne'82, Goldberg'84]
- Reduction to submodular function minimization [folklore]
- LP relaxation [Charikar'00]

### Sub and Supermodularity

Real-valued set function  $f: 2^V \to R$  is **submodular** if  $f(A) + f(B) \ge f(A \cap B) + f(A \cup B) \quad \forall A, B$ Equivalently:

 $f(A + v) - f(A) \ge f(B + v) - f(B) \quad A \subset B, v \notin B$ 



#### Sub and Supermodularity

 $f: 2^V \rightarrow R$  is supermodular iff -f is submodular

 $f(A) + f(B) \le f(A \cap B) + f(A \cup B) \quad \forall A, B$ Marginal value:  $f(v \mid S) = f(S + v) - f(S)$ Supermodular:

 $f(v \mid B) \ge f(v \mid A) \qquad A \subset B, v \in B - A$ 

# Sub and Supermodularity

Given graph G = (V, E)

- $f(S) = |\delta(S)|$  is submodular and non-neg
- $f(S) = |E(S)| = \frac{1}{2} (\sum_{v} \deg(v) |\delta(S)|)$  is supermodular, nonnegative and monotone



### Densest Supermodular Set (DSS)

Given supermodular  $f: 2^V \to R_+$  find  $\max_{S} \frac{f(S)}{|S|}$ 

**Decision version:** check if  $\exists S \ s.t \quad \frac{f(S)}{|S|} \ge \lambda$ 

Check if  $\exists S \ s.t \ \lambda |S| - f(S) \le 0$ 

Poly-time via submodular function minimization

# Some Recent Directions on Densest Subgraph Discovery

- Fast *approximate* algorithms for *(very) large* graphs
- Variations in objective and applications
- Streaming (approximate) algorithms
- Parallel (approximate) algorithms
- Dynamic (approximate) algorithms

# My Motivation

- Conjecture of [Boob-Gao-Peng-Sawlani-Tsourkakis-Wang-Wang'20] on a simple iterative greedy alg.
- Faster approximations for mixed packing and covering LPs (DSG is a special case)

- Connections to supermodularity
- Discrete + continuous

# Results at high-level

- Fast approximate algorithm:  $(1 \epsilon)$  approximation for densest subgraph in  $O\left(m\frac{polylog(n)}{\epsilon}\right)$  time
- Affirmative answer to conjecture of [Boob et al]
- Generalization to supermodular functions
- Other results ...

**Connections** which are simple in retrospect but helpful for both theory and practice

# Papers

- Densest Subgraph: Supermodularity, Iterative Peeling, and Flow [CQT SODA'22]
- Faster and Scalable Algorithms for Densest Subgraph and Decomposition [HQC NeuRIPS'22]
- $(1 \epsilon)$ -approximate fully dynamic densest subgraph: linear space and faster update time [CQ'22/23]
- Convergence to Lexicographically Optimal Base in a (Contra)Polymatroid and Applications to Densest Subgraph and Tree Packing [HQC '23]
- On the Generalized Mean Densest Subgraph Problem: Complexity and Algorithms [CT'23]

### Rest of the talk

- Charikar's LP Relaxation
- Peeling and Iterative Peeling
- Connections and ideas about proof of convergence

#### Charikar's LP Relaxation

Integer Programming Formulation

 $\max \frac{\sum_{uv \in E} x_{uv}}{\sum_{v} z_{v}}$ 

 $x_{uv} \le \min(z_u, z_v) \quad uv \in E$ 

*x*, *z* binary variables

 $\max_{S} \frac{|E(S)|}{|S|}$ 

 $z_v \in \{0,1\} \ v \in S?$  $x_{uv} \in \{0,1\} \ uv \in E(S)?$ 



Theorem: [Charikar'00] LP is optimal for DSG



**Theorem:** [Charikar'00] LP is optimal for DSG

### Flow Reduction via Dual

Observed in [Boob et al]

 $\min D$  $y_{uv,u} + y_{uv,v} \ge 1 \quad uv \in E$  $\sum_{uv \in E} y_{uv,v} \le D \quad v \in V$  $y \ge 0$ 

Fractional perfect matching



**Claim:** Max-flow in  $H_{\lambda} = |E|$  iff  $\lambda \ge \lambda^*$ 

# Utility of LP

- Dual LP can be viewed as a flow problem --- simpler formulation than [Goldberg,Picard-Queyranne].
  Dual LP computes *fractional arboricity*. λ\* = *fractional arboricity*
- Dual LP is mixed-packing and covering LP. Hence can solve via approximate methods [Bahmani-Goel-Munagala'14] [Boob-Sawlani-Wang'19]
- More connections soon

#### Flow based Approx Algorithm

#### [CQT'22]

**Theorem:**  $(1 - \epsilon)$  approximation for DSG in  $O\left(m\frac{polylog(n)}{\epsilon}\right)$  time via *approximate* flow

**Improvement:**  $\frac{1}{\epsilon}$  instead of  $\frac{1}{\epsilon^2}$ 

Key structural idea: short (length  $\leq c \log n / \epsilon$ ) augmenting paths suffice to get  $(1 - \epsilon)$  approximation

Empirical utility of idea not yet unexplored

# Peeling Algorithm

#### [Asahiro etal 00, Charikar 00]

- For i = 1 to n do
  - $v_i$  is in *min-degree* vertex in *G*
  - $G \leftarrow G v_i$
- $v_1, v_2, ..., v_n$  is *ordering* created by algorithm

• 
$$S_i \leftarrow \{v_i, v_{i+1}, \dots, v_n\}$$

• Output  $argmax_i \frac{|E(S_i)|}{|S_i|}$ 

**Theorem:** [Charikar'00] Greedy peeling is a <sup>1</sup>/<sub>2</sub> approximation for DSG (proof via LP)

# (Tight) Example



# (Tight) Example



Given supermodular function  $f: 2^V \rightarrow R_+$ 

- For i = 1 to n do
  - $v_i \leftarrow argmin_v f(v \mid V v)$

• 
$$V \leftarrow V - v_i$$

- Restrict f to  $V v_i$
- $v_1, v_2, ..., v_n$  is ordering created by algorithm

• 
$$S_i \leftarrow \{v_i, v_{i+1}, \dots, v_n\}$$

• Output  $argmax_i \frac{|f(S_i)|}{|S_i|}$ 

**Question:** How can we characterize for general *f*?

$$c_f = \max_{S} \frac{\sum_{v \in S} f(v \mid S - v)}{f(S)}$$

Supermodularity:

$$\sum_{v \in S} f(v \mid S - v) \ge f(S) \Rightarrow c_f \ge 1$$

$$c_f = \max_{S} \frac{\sum_{v \in S} f(v \mid S - v)}{f(S)}$$

**Theorem:** Peeling is a  $\frac{1}{c_f}$  approximation for DSS

Proof is a simple adaptation of the combinatorial proof for DSG [Khuller-Saha'09]

Can also do it via relaxation ala [Charikar'00]

**Theorem:** Peeling is a  $\frac{1}{c_f}$  approximation for DSS

- Graphs:  $c_f = \max_{S} \frac{\sum_{v \in S} \deg(v,S)}{|E(S)|} = 2$
- Hypergraphs:  $c_f = r$  where r is rank
- p-th mean in graphs:  $c_f = p + 1$

Unifies all the known bounds on greedy peeling

## Iterative Peeling

#### [BGPSTWW'20]

- Heuristic inspired by Dual-LP and MWU
- Goal: improve  $\frac{1}{2}$  approx to  $(1 \epsilon)$  approx.
- Peel several times by adjusting "load"
- Creates a new ordering in each iteration
- Pick best suffix among all orderings

# Iterative Peeling

#### [BGPSTWW'20]

#### Greedy++

- load(v, 0) = 0 for all v
- For t = 1 to T do
  - $G' \leftarrow G$
  - For i = 1 to n do
    - $v_{t,i} \leftarrow argmin_v \deg(v) + load(v, t 1)$
    - $load(v_{t,i},t) = load(v_{t,i},t-1) + deg(v_{t,i})$
    - $G' \leftarrow G' v_{i,t}$
- $S_{t,i} \leftarrow \{v_{t,i}, \dots, v_{t,n}\}$
- Output  $argmax_{i,t} \frac{|E(S_{t,i})|}{|S_{t,i}|}$







### Conjecture

#### [BGPSTWW'20]

**Conjecture:** Greedy++ is a  $(1 - \epsilon)$  approximation after  $O\left(\frac{1}{\epsilon^2}\right)$  iterations for DSG

Seems to work very well in practice. Implementation runs very fast even on large graphs and converges quickly on many real-world graphs

#### Iterative Peeling for DSS

Given supermodular  $f: 2^V \to R_+$  find  $\max_{S} \frac{f(S)}{|S|}$ 

#### SuperGreedy++

- load(v,0) = 0 for all v
- For t = 1 to T do
  - $S_{t,0} \leftarrow V$
  - For i = 1 to n do
    - $v_{t,i} \leftarrow argmin_{v \in S_{t,i}} f(v|S_{t,i} v) + load(v, t 1)$
    - $load(v_{t,i}, t) = load(v_{t,i}, t-1) + f(v_{t,i}|S_{t,i} v_{t,i})$
    - $S_{t,i+1} \leftarrow S_{t,i} v_{t,i}$

• Output  $argmax_{t,i} \frac{|f(s_{t,i})|}{|s_{t,i}|}$ 

### Iterative Peeling for DSS

#### [CQT'22]

**Theorem:** SuperGreedy++ converges to a  $(1 - \epsilon)$  approximation in  $O(\frac{1}{\epsilon^2} \frac{\max f(v)}{\lambda^*} \log n)$  iterations

**Corollary:** Greedy++ converges to a  $(1 - \epsilon)$ approximation for DSG in  $O(\frac{1}{\epsilon^2} \frac{\Delta(G)}{\lambda^*} \log n)$  iterations

### Proof Idea

- Express DSS as an LP relaxation
  - Generalize Charikar's LP for DSG via Lovaszextension of supermodular/submodular functions
  - Rewrite as LP via an *ordering based* view of Lovaszextension
- Relate SuperGreedy++ iterations to a multiplicativeweight update (MWU) algorithm via LP
  - SuperGreedy++ iterations are *not* MWU iterations but can show *approximate* relationship which is the main technical part

# Different Perspective/Proof

#### [HQC'22, 23]

- Focus on DSS
- Make connection to principal partition of sub/supermodular function
- Fujishige's result on lexicographically optimal base in a polymatroid
- Frank-Wolfe method and convergence analysis

### Dense Subgraph Decomposition

**Lemma:** There is a **unique maximal** "densest" subgraph in any graph **G** 

Suppose A and B are *maximal* sets with density  $\lambda^*$ 

- 1.  $f(A) + f(B) \le f(A \cup B) + f(A \cap B)$
- 2.  $|A| + |B| = |A \cup B| + |A \cap B|$

Implies  $A \cup B$  has density  $\lambda^*$ 

#### Dense Decomposition

Fix supermodular function  $f: 2^V \rightarrow R_+$  (monotone, non-negative)

 $S_1$  is unique maximal densest set for f with density  $\lambda_1$ Function  $f_{S_1}: 2^{V-S_1} \to R_+$  obtained by *contracting*  $S_1$ (also supermodular)

 $S_2$  is unique maximal densest set for  $f_{S_1}$  with density  $\lambda_2$ Observation:  $\lambda_1 > \lambda_2$ 

### Dense Subgraph Decomposition

Fix supermodular function  $f: 2^V \rightarrow R_+$  (monotone, non-negative)

Can partition *V* into  $S_1, S_2, ..., S_k$  with decreasing densities  $\lambda_1 > \lambda_2 > \cdots > \lambda_k$ 

Called the dense (subgraph) decomposition

For each  $v \in S_i$  associate  $\lambda(v) = \lambda_i$ 

 $\overline{\lambda} \in \mathbb{R}^{V}$  the dense decomposition vector

### Dense Subgraph Decomposition



#### Dense Decomposition

Fix supermodular function  $f: 2^V \rightarrow R_+$  (monotone, non-negative)

Alternatively: consider

 $\max f(S) - \lambda |S|$  as  $\lambda$  varies from  $-\infty$  to  $\infty$ 

Optimum changes only a finite number of times corresponding to *nested family* of sets:  $S_1, S_1 \cup S_2, S_1 \cup S_2 \cup S_3, \dots, V = S_1 \cup S_2 \dots \cup S_k$ 

Well-studied in graph/matroid/submodular literature: survey by Fujishige "Theory of Principal Partitions Revisited"

## Computing Dense Decomposition Vector

#### [Fujishige'80]

**Theorem:** Dense decomposition vector  $\overline{\lambda}$  is the *unique lexicographically minimal base* in the contra polymatroid associated with **f** 

Fujishige considered submodular functions but can be easily adapted to supermodular functions

### Polymatroid

Suppose  $g: 2^V \to R_+$  is a monotone *submodular* function such that  $g(\emptyset) = 0$  (normalized)

[Edmonds] *polymatroid* associated with **g** is the polytope in  $\mathbb{R}^{n}$  (here n = |V|)

 $x(S) \le f(S)$  for all  $S \subseteq V$  $x_v \ge 0$  for all  $v \in V$ 

## Contra Polymatroid

Suppose  $f: 2^V \to R_+$  is a monotone *supermodular* function such that  $f(\emptyset) = 0$  (normalized)

Contra polymatroid associated with **f** is the polytope in  $R^n$  (here n = |V|)

 $x(S) \ge f(S)$  for all  $S \subseteq V$  $x_v \ge 0$  for all  $v \in V$ 

#### Base Contra Polymatroid

Suppose  $f: 2^V \to R_+$  is a monotone *supermodular* function such that  $f(\emptyset) = 0$  (normalized)

Base Contra polymatroid associated with f is the polytope

$$\begin{aligned} x(S) &\geq f(S) & for all S \subseteq V \\ x(V) &= f(V) \\ x_v &\geq 0 & for all v \in V \end{aligned}$$

Each vector  $y \in B_f$  is a **base** of f

# Lexicographically optimal base & Dense Decomposition

[Fujishige'80] (interpreted/paraphrased)

**Theorem:**  $f: 2^V \rightarrow R_+$  is a monotone *supermodular* function and let  $B_f$  be its base contra polymatroid. Then there is a unique lexicographically minimum base  $y^*$  and

1.  $y^* = \overline{\lambda}$ 

2. max density  $\lambda_1 = \min \max_{v} x_v \ s.t \ x \in B_f$  (an LP)

3.  $y^*$  is the unique opt solution to *quadratic* program

 $\min \sum_{v} x_{v}^{2} \quad s.t \ x \in B_{f}$ 

#### Back to DSG

Recall for densest subgraph: f(S) = |E(S)|

What is Fujishige's "relaxation"?

Variable  $x_v$  for each vertex  $v \in V$ 

 $\begin{array}{l} \min D \\ x_{v} \leq D \ for \ all \ v \in V \\ \sum_{v} x_{v} = m \\ \sum_{v \in S} x_{v} \geq |E(S)| \ for \ all \ S \subseteq V \\ x_{v} \geq 0 \ for \ all \ v \in V \end{array}$ 

### Back to DSG

#### [HQC'22]

**Question:** How is this exponential sized LP related to Charikar's LP?

- Dual of Charikar's LP is "equivalent" to Fujishige's relaxation!
- Charikar's LP can be viewed as a compact extended formulation that is specific to DSG
- Charikar's primal LP can be recast via the Lovasz extension of supermodular function

# Frank-Wolfe for solving QP

Optimum solution to quadratic program:

 $\min \sum_{v} x_{v}^{2} \quad \text{such that } x \in B_{f}$ 

is the dense decomposition vector

How do we solve this quadratic program?

Frank-Wolfe from convex optimization is ideal because *linear optimization* over  $B_f$  is easy: greedy algorithm is optimal for polymatroid/contra polymatroids [Edmonds]

# Frank-Wolfe for solving QP

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Back to Greedy++ and SuperGreedy++

- SuperGreedy++ is **not** Frank-Wolfe on Fujisghige's QP
- So, what is it?
- Main claim: SuperGreedy++ is a *noisy* or *approximate* version of a *variant* of Frank-Wolfe
- Can generalize Frank-Wolfe convergence analysis to show that SuperGreedy++ also converges
- New proof has weaker convergence bound but gives additive guarantees. Also shows that SuperGreedy++ converges to the full dense decomposition vector rather than just max density

# Iterative Algorithms for DSG and Empirical Evaluation

#### [HQC NeuRIPS'22]

- Focus on DSG and dense graph decomposition
- Algorithms
  - 1. Greedy++
  - 2. Frank-Wolfe on quadratic program starting with greedy solution as starting point [Danisch-Chan-Sozio'17]
  - 3. Accelerated proximal gradient method on quadratic program (FISTA). Main observation is that projection oracle is O(m) time so iterations are quite fast and parallelizable.
  - 4. MWU based algorithm
- Unlike Greedy++ other algorithms produce "fractional" solutions and need to be rounded. Introduce "fractional peeling" a heuristic with some theoretical support





Iterative Algorithms for DSG and Empirical Evaluation

#### [HQC NeuRIPS'22]

- FISTA based algorithm seems to be the consistent winner but Greedy++, Frank-Wolfe also competitive. MWU quite slow
- Fractional peeling is very important for performance

See paper for detailed plots

### Take aways

- SuperGreedy and SuperGreedy++: simple iterative algorithms for *any supermodular density function*
- For DSG, a new FISTA based algorithm that seems superior to other methods. Fractional peeling for rounding that applies for other methods as well
- Frank-Wolfe vs SuperGreedy++: former competitive but fractional while latter is "combinatorial"
- p-mean DSG is NP-Hard for p < 1. See [CT'23] for results and open problems

# Open Problem

Tight analysis of Greedy++

- Recall conjecture is  $O\left(\frac{1}{\epsilon^2}\right)$  iterations
- Worst example known to us:  $\Omega\left(\frac{1}{\epsilon}\right)$  iterations for  $(1 \epsilon)$  approximation
- Our bound:  $O(\frac{1}{\epsilon^2} \frac{\Delta(G)}{\lambda^*} \log n)$

